Learned Image and Video Compression with Deep Neural Networks



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Part 1 Learned Image Compression



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7296 x 5472 = 39,923,712 pixels

Uncompressed image: 39,923,712 x 3 = 120 MB

Uncompressed video (60 fps): 120 MB x 60 = 7.2 GBps (18s needs 128 GB)

Lossless compression (.png): 44 MB Lossy compression (.jpg): 9 MB

Image/video compression plays an important role in multimedia streaming, online conference, data storage, etc.

Rate-distortion trade-off



Higher bit-rate (file size)

Traditional Image Compression

• Classical Architecture:



- Standards: JPEG (DCT + Huffman), JPEG2000 (DWT + Arithmetic coding), BPG (HEVC), …
- Example: JPEG compression framework



Entropy coding

Entropy:

$$\mathrm{H}(X) = \mathrm{E}[\mathrm{I}(X)] = \mathrm{E}[-\log(\mathrm{P}(X))]$$

$$\operatorname{H}(X) = -\sum_{i=1}^n \operatorname{P}(x_i) \log_b \operatorname{P}(x_i)$$

Cross entropy:

$$H(p,q) = -\sum_{x \in \mathcal{X}} \frac{p(x)}{\mathsf{real}} \log \frac{q(x)}{\mathsf{estimated}}$$
 (Eq.1)

(Adaptive) arithmetic coding is theoretically able to losslessly compress data at

• bit-rate \cong cross entropy (with little overhead)

Arithmetic coding:

- 60% chance of symbol NEUTRAL
- 20% chance of symbol POSITIVE
- 10% chance of symbol NEGATIVE
- 10% chance of symbol END-OF-DATA.





• Basic architecture ^[1]: End-to-end trainable



[1] Ballé, Johannes, et al. "End-to-end optimized image compression." in ICLR. 2017.

• CNN transformer + **factorized** entropy model^[1]



$$\begin{split} \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \text{Training: differentiable quantization (not differentiable)} \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \text{Inference: quantization (not differentiable)} \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \text{Inference: quantization (not differentiable)} \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y} + \Delta \mathbf{y} \sim \mathcal{U}(0,1) \\ \tilde{\mathbf{y}} = \mathbf{y}$$

[1] Ballé, Johannes, et al. "End-to-end optimized image compression." in ICLR. 2017.

• CNN transformer + hyperpiror entropy model ^[2]



(factorized)

(hyperprior)



[2] Ballé, Johannes, et al. "Variational image compression with a scale hyperprior." in ICLR. 2018.

• CNN transformer + autoregressive entropy model ^[3] ^{*}_D



Due to the chain rule:	$p(y) = p(y_1) \cdot p(y_2 y_1) \cdot p(y_3 y_2, y_1) \dots p(y_N y_{N})$
$p_{\hat{\boldsymbol{y}} \hat{\boldsymbol{z}}}(\hat{\boldsymbol{y}} \hat{\boldsymbol{z}}) = \prod_{i=1}^{N} \underline{p_{\hat{y}_i \hat{y}_{< i}, \hat{\boldsymbol{z}}}(\hat{y}_i \hat{y}_{< i}, \hat{\boldsymbol{z}})}$	$ \hat{y}_{< i}, oldsymbol{\hat{z}})$
$p_{oldsymbol{\hat{y}}}(oldsymbol{\hat{y}} \mid oldsymbol{\hat{z}}, oldsymbol{ heta}_{hd}, oldsymbol{ heta}_{cm}, oldsymbol{ heta}_{ep}) = \prod_i$	$\left(\mathcal{N}(\mu_i, \sigma_i^2) * \mathcal{U}\left(-\frac{1}{2}, \frac{1}{2}\right)\right)(\hat{y}_i)$
with μ_i, σ_i =	$=g_{ep}(oldsymbol{\psi},oldsymbol{\phi}_i;oldsymbol{ heta}_{ep}),oldsymbol{\psi}=g_h(oldsymbol{\hat{z}};oldsymbol{ heta}_{hd}), ext{and}\ oldsymbol{\phi}_i=g_{cm}(oldsymbol{\hat{y}}_{< i};oldsymbol{ heta}_{cm})$



Mask CNN^[4]

Symbol

 $oldsymbol{x}$

 $f(\boldsymbol{x};\boldsymbol{\theta}_e)$

 $oldsymbol{y}$

ŷ

 $g(\hat{\boldsymbol{y}}; \boldsymbol{\theta}_d)$

 $f_h(\boldsymbol{y}; \boldsymbol{\theta}_{he})$

z

ź

 $g_h(\boldsymbol{\hat{z}}; \boldsymbol{\theta}_{hd})$

 $g_{cm}(\underline{y_{< i}}; \theta_{cm})$

 $g_{ep}(\cdot; \boldsymbol{\theta}_{ep})$

 \hat{x}





R

1	1	1
1	1	0
0	0	0

other layers

Algorithm 1 Constructing 3D Masks

1: central_idx $\leftarrow \left[(f_W \cdot f_H \cdot f_D)/2 \right]$ 2: *current_idx* \leftarrow 1 3: $mask \leftarrow f_W \times f_H \times f_D$ -dimensional matrix of zeros 4: for $d \in \{1, \ldots, f_D\}$ do for $h \in \{1, ..., f_H\}$ do 5: for $w \in \{1, ..., f_W\}$ do 6: if current_idx < central_idx then 7: mask(w, h, d) = 18: 9: else mask(w, h, d) = 010: $current_idx \leftarrow current_idx + 1$ 11:

[3] Minnen, David, et al. "Joint autoregressive and hierarchical priors for learned image compression." in NeruIPS. 2018.[4] Mentzer, Fabian, et al. "Conditional Probability Models for Deep Image Compression", in CVPR, 2018.

• CNN transformer + **autoregressive** entropy model $\begin{bmatrix} 5 \end{bmatrix}_{D}^{\mathbf{I}}$



[5] Lee, Jooyoung, et al. "Context-adaptive Entropy Model for End-to-end Optimized Image Compression." in ICLR. 2019.



 $y_i \in \{\text{hot coffee, hot tea, cold coffee, cold tea}\}$ $y = [y_1, y_2, y_3]$

• Factorized entropy model

 $p_{y_i}(y_i) = 25\%$ for y_i = hot coffee, hot tea, cold coffee, cold tea $H(p_{y_i}) = 4 \times (-0.25 \log_2 0.25) = 2$

The expected number of bits to encode y is 6

• Hyperprior entropy model $z = [10^{\circ}C, 15^{\circ}C, 30^{\circ}C]$

 $p_{y_i|z_i}(y_i|z_i < 20^{\circ}\text{C}) = 50\%$ for $y_i = \text{hot coffee, hot tea}$ $H = 2 \times (-0.5 \log_2 0.5) = 1$

 $p_{y_i|z_i}(y_i|z_i \ge 20^{\circ}\text{C}) = 50\%$ for $y_i = \text{cold coffee, cold tea}$ H = 1

The expected number of bits to encode y is 3

• Autoregressive entropy model (joint with hyperprior)

 $p_{y_i|y_{i-1},z_i}(y_i|y_{i-1},z_i)$ Don't drink coffee (or tea) in two consecutive days. $z = [10^{\circ}\text{C}, 15^{\circ}\text{C}, 30^{\circ}\text{C}]$ p(y = [hot coffee, hot tea, cold coffee]) = 0.5 p(y = [hot tea, hot coffee, cold tea]) = 0.5The expected number of bits to encode y is $H(y) = 2 \times (-0.5 \log_2 0.5) = 1$

• Another differentiable quantization method ^[4] given centers $C = \{c_1, \dots, c_L\}$

$$\hat{z}_{i} = Q(z_{i}) := \arg \min_{j} ||z_{i} - c_{j}||$$
$$\tilde{z}_{i} = \sum_{j=1}^{L} \frac{\exp(-\sigma ||z_{i} - c_{j}||)}{\sum_{l=1}^{L} \exp(-\sigma ||z_{i} - c_{l}||)} c_{j}$$

Inference

Training: differentiable

• Importance map^[4]



[4] Mentzer, Fabian, et al. "Conditional Probability Models for Deep Image Compression", in CVPR, 2018.







- Another differentiable quantization method ^[4]
 given centers C = {c₁, · · · , c_L}
 - $\hat{z}_{i} = Q(z_{i}) := \arg \min_{j} ||z_{i} c_{j}||$ $\tilde{z}_{i} = \sum_{j=1}^{L} \frac{\exp(-\sigma ||z_{i} c_{j}||)}{\sum_{l=1}^{L} \exp(-\sigma ||z_{i} c_{l}||)} c_{j}$
 - Inference

Training: differentiable

 \boldsymbol{x} g_p g_a \hat{z} \hat{x} \hat{y} g_p g_s perceptual data code D Rspace space space

$$\bar{z}_i = \text{tf.stopgradient}(\hat{z}_i - \tilde{z}_i) + \tilde{z}_i$$

Importance map^[4]



• Gaussian Mixture Model (GMM) for entropy [6]

$$p_{\hat{\boldsymbol{y}}|\hat{\boldsymbol{z}}}(\hat{\boldsymbol{y}}|\hat{\boldsymbol{z}}) \sim \sum_{k=1}^{K} \boldsymbol{w}^{(k)} \mathcal{N}(\boldsymbol{\mu}^{(k)}, \boldsymbol{\sigma}^{2(k)})$$

[4] Mentzer, Fabian, et al. "Conditional Probability Models for Deep Image Compression", in CVPR, 2018.[6] Cheng et al. "Learned Image Compression with Discretized Gaussian Mixture Likelihoods and Attention Modules", in CVPR. 2020.

• CNN transformer + coarse-to-fine model [7]





[7] Hu, Yueyu, et al. "Coarse-to-Fine Hyper-Prior Modeling for Learned Image Compression." in AAAI. 2020.

• Performance





Comparison on Tecnick image set



The rank may vary on different datasets

The context (autoregressive) and coarse-to-fine models outperform BPG 4:4:4 (latest traditional standard)

• Variable rate image compression: RNN-based methods ^[8, 9]



[8] Toderici, George, et al. "Variable Rate Image Compression with Recurrent Neural Networks." in ICLR. 2016.[9] Toderici, George, et al. "Full Resolution Image Compression with Recurrent Neural Networks." in CVPR, 2017.

• Variable rate image compression: RNN-based methods ^[10]



[10] Johnston, Nick, et al. "Improved Lossy Image Compression with Priming and Spatially Adaptive Bit Rates for Recurrent Networks." in CVPR. 2018.

• Variable rate image compression: Conditional autoencoder ^[11]

Loss function: $\min_{\phi,\theta} \{ D_{\phi,\theta} + \underline{\lambda} R_{\phi} \}$ $\min_{\phi,\theta} \sum_{\lambda \in \Lambda} \left(D_{\phi,\theta}(\lambda) + \lambda R_{\phi,\theta}(\lambda) \right)$ $\min_{\phi,\theta} \sum_{\lambda \in \Lambda} \mathbb{E}_{p(\Delta)} [D_{\phi,\theta}(\lambda, \Delta) + \lambda R_{\phi,\theta}(\lambda, \Delta)]$ 42 Averaged PSNR (dB) on 24 Kodak images 40 38 PSNR (dB) 36 $\lambda = 10^{-1.5}, \Delta \in [0.5, 2]$ 34 $\lambda = 10^{-2.0}, \Delta \in [0.5, 2]$ 32 $\lambda = 10^{-2.5}, \Delta \in [0.5, 2]$ 30 $\lambda = 10^{-3.0}, \Delta \in [0.5, 2]$ 28 $\lambda \,{=}\, 10^{-3.5}, \Delta \,{\in}\, [0.\,5,2]$ 26∟ 0.0 0.5 1.0 1.5 2.0 Bits per pixel (BPP)



[11] Choi, Yoojin, et al. "Variable Rate Deep Image Compression With a Conditional Autoencoder." in ICCV. 2019.

• Variable rate image compression: Conditional autoencoder ^[11]



[11] Choi, Yoojin, et al. "Variable Rate Deep Image Compression With a Conditional Autoencoder." in ICCV. 2019.

• Variable rate image compression: Wavelet-like transformer ^[12]



Invertible: achieving lossy and lossless compression by the same framework



[12] Ma, Haichuan, et al. "End-to-End Optimized Versatile Image Compression With Wavelet-Like Transform." in IEEE T-PAMI. 2020.

• Variable rate image compression: Wavelet-like transformer ^[12]



[12] Ma, Haichuan, et al. "End-to-End Optimized Versatile Image Compression With Wavelet-Like Transform." in IEEE T-PAMI. 2020.

1.5

1.7

• Generative image compression: GAN-based methods ^[13]







[13] Agustsson, Eirikur, et al., "Generative adversarial networks for extreme learned image compression." in ICCV. 2019.

• Generative image compression: GAN-based methods ^[13]



Conditional GAN: $\mathcal{L}_{cGAN} := \max_{D} \mathbb{E}[f(D(\boldsymbol{x}, \boldsymbol{s}))] + \mathbb{E}[g(D(G(\boldsymbol{z}, \boldsymbol{s}), \boldsymbol{s}))]$ Selective generative compression (SC): binary heatmap \boldsymbol{m}



road (0.146bpp, -55%)

car (0.227bpp, -15%)

all synth. (0.035bpp, -89%)



people (0.219bpp, -33%) *building* (0.199bpp, -39%) no synth. (0.326bpp, -0%) [13] Agustsson, Eirikur, et al. "Generative adversarial networks for extreme learned image compression." in ICCV. 2019.

• Generative image compression: GAN-based methods ^[14]

High-Fidelity Generative Image Compression



Conditional discriminator:

$$\mathcal{L}_{EGP} = \mathbb{E}_{x \sim p_X} [\lambda r(y) + d(x, x') - \beta \log(D(x', y))],$$

$$\mathcal{L}_D = \mathbb{E}_{x \sim p_X} [-\log(1 - D(x', y))] + \mathbb{E}_{x \sim p_X} [-\log(D(x, y))].$$

[14] Mentzer, Fabian, et al. "High-Fidelity Generative Image Compression." in NeurIPS. 2020.

• Generative image compression: GAN-based methods ^[14]



[14] Mentzer, Fabian, et al., "High-Fidelity Generative Image Compression." in NeurIPS. 2020.

Conclusion:

- CNN-based methods
 - Factorized entropy model
 - Hyperprior entropy model
 - Autoregressive entropy model
 - Coarse-to-fine entropy model
 - Conditional auto-encoder (variable bit-rates)
 - Invertible auto-encoder (lossy and lossless by one framework)
- RNN-based methods
 - Variable bit-rate
- GAN-based methods
 - Photo-realistic compressed image with low bit-rate

The state-of-the-art learned image compression methods successfully outperform the latest traditional compression standard BPG 4:4:4





- Will learning-based compression be standardized?
- Can learning-based method be compatible with traditional standards (e.g., JPEG)?

JPEG initiates standardisation of image compression based on AI

The 89th JPEG meeting was held online from 5 to 9 October 2020.

During this meeting multiple JPEG standardisation activities and explorations were discussed and progressed. Notably, the call for evidence on learning-based image coding was successfully completed and evidence was found that this technology promises several new functionalities while offering at the same time superior compression efficiency, beyond the state of the art.

JPEG AI

At the 89th meeting the submissions to the Call for Evidence on learning-based image coding were presented and discussed. Four submissions were received in response to the Call for Evidence. The results of the subjective evaluation of the submissions to the Call for Evidence were reported and discussed in detail by experts. It was agreed that there is strong evidence that learning-based image coding solutions can outperform the already defined anchors in terms of compression efficiency, when compared to state-of- the-art conventional image coding architecture. Thus, it was decided to create a new standardisation activity for a JPEG AI on learning-based image coding system, that applies machine learning tools to achieve substantially better compression efficiency compared to current image coding systems, while offering unique features desirable for an efficient distribution and consumption of images. This type of approach should allow to obtain an efficient compressed domain representation not only for visualisation, but also for machine learning based image processing and computer vision. JPEG AI releases to the public the results of the objective and subjective evaluations as well as a first version of common test conditions for assessing the performance of leaning-based image coding systems.

- Will learning-based compression be standardized?
- Can learning-based method be compatible with traditional standards (e.g., JPEG)?

We made an attempt: ^[15]



[15] Strümpler, Yannick, et al. "Learning to Improve Image Compression without Changing the Standard Decoder." in ECCVW. 2020.

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- Will learning-based compression be standardized?
- Can learning-based method be compatible with traditional standards (e.g., JPEG)?

We made an attempt: ^[15]



- We achieve better rate-distortion performance without changing the standard decoder
- The compressed image can be decoded (viewed) on any common device, e.g., mobile, ipad, PC, etc.

[15] Strümpler, Yannick, et al. "Learning to Improve Image Compression without Changing the Standard Decoder." in ECCVW. 2020.

- Open source codes:
 - Ballé et al., (factorized), Ballé et al., (hyperprior): https://github.com/tensorflow/compression (TensorFlow)
 - Ballé et al., (factorized), Ballé et al., (hyperprior), Minnen et al., (autoregressive): https://interdigitalinc.github.io/CompressAl/index.html (PyTorch)
 - Lee et al., (context-adaptive):

https://github.com/JooyoungLeeETRI/CA_Entropy_Model

• Mentzer et al., (autoregressive + importance map):

https://github.com/fab-jul/imgcomp-cvpr

• Cheng et al., (GMM entropy model):

https://github.com/ZhengxueCheng/Learned-Image-Compression-with-GMM-and-Attention

• Hu et al., (coarse-to-fine):

https://github.com/huzi96/Coarse2Fine-ImaComp

• Ma et al., (wavelet-like transformer):

https://github.com/mahaichuan/Versatile-Image-Compression

• Mentzer et al., (generative compression):

https://github.com/tensorflow/compression/tree/master/models/hific

Thanks for your attention

Q & A



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Learned Image and Video Compression with Deep Neural Networks

PART 2: Learned Video Compression

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VCIP, December 1-4, 2020 IEEE VCIP 2020

Outline

- Background for Video Compression
- End-to-end Learned P-frame Compression
- End-to-end Learned B-frame Compression
- Learned Autoencoder based Video Compression
- Discussion
Background for Video Compression

Traditional codecs rely on classical prediction-transform architecture and handcrafted techniques.



Deep learning has been widely used for a lot of vision tasks for its powerful representation ability.

What happens when video compression meets deep learning?

Background for Video Compression

Traditional Video Compression





• The first end-to-end optimized video compression system^[1]



[1]Guo Lu, et al. "DVC: An end-to-end deep video compression framework", in CVPR(Oral), 2019.

- Flexible Framework^[1,2]
 - Advanced entropy model for motion/residual compression with autoregressive entropy -> reduce bitrate
 - Motion and Residual Refinement -> reduce distortion
- Variable Bitrate Solution
 - Adaptive quantization layer -> feature transformation between different rates



[1]Guo Lu, et al. "DVC: An end-to-end deep video compression framework", in CVPR(Oral), 2019. [2]Guo Lu, et al. "An End-to-End Learning Framework for Video Compression," in T-PAMI. 2020.



[1]Guo Lu, et al. "DVC: An end-to-end deep video compression framework", in CVPR(Oral), 2019. [2]Guo Lu, et al. "An End-to-End Learning Framework for Video Compression," in T-PAMI. 2020.

- RDO is the fundamental technique for video compression
 - Choose the optimal mode in the coding stage, such as motion vector, block size, etc.
- Learning based video compression
 - RDO is ignored in the inference stage
 - the "modes" are fixed after the training stage
- How to apply the RDO technique in learned video compression
 - Directly optimize the encoder
 - Introduce more "modes" and select the optimal

1. Lack of adaptiveness to different video content^[3]



Once the training procedure is finished, the parameters in the learning based encoder are fixed

2. Error propagation in inter predictive coding



Quality keeps decreasing because the error propagation is not considered in the training procedure



Online Encoder Updating Scheme Error Propagation Aware Training Strategy



1. Online Encoder Updating Scheme



Improve adaptiveness with Same decoding time





All methods use same GoP settings

[3]Guo Lu, Chunlei Cai, et al. "Content Adaptive and Error Propagation Aware Deep Video Compression", in ECCV(Oral), 2020.



All methods use same GoP settings

[3]Guo Lu, Chunlei Cai, et al. "Content Adaptive and Error Propagation Aware Deep Video Compression", in ECCV(Oral), 2020.

All methods use same GoP settings

Table 1: The BDBR and BD-PSNR results of different algorithms when compared with H.264. Negative values in BDBR represent the bitrate saving.

	BDBR(%)			BD-PSNR(dB)		
Dataset	H.265	DVC	Ours	H.265	DVC	Ours
Class B	-32.0	-27.9	-41.7	0.78	0.71	1.12
Class C	-20.8	-3.5	-25.9	0.91	0.13	1.18
Class D	-12.3	-6.2	-25.1	0.57	0.26	1.25





- Various block sizes are adopted in traditional video compression
 - Large block size for smooth region
 - Small block size for complex region
- Fixed optical flow resolution and motion representation resolutions are used in existing work, like DVC.
 - Generates more mode -> flow resolutions or representation resolutions
 - Choose the optimal mode using RDO



- (a) Overview of the proposed video compression system.
- (b) RaFC-Frame: decides the Global Optimal Flow Map resolution for each video frame.
 (c) RaFC-Block: select the optimal resolution for each

Local Block of motion feature







Generate multi-scale
motion features

 Select the optimal resolution of the motion features for each block



[4] Zhihao Hu, et al. "Improving Deep Video Compression by Resolution-adaptive Flow Coding", in ECCV(Oral), 2020.



[4] Zhihao Hu, et al. "Improving Deep Video Compression by Resolution-adaptive Flow Coding", in ECCV(Oral), 2020.





(a)

(b)



[4] Zhihao Hu, et al. "Improving Deep Video Compression by Resolution-adaptive Flow Coding", in ECCV(Oral), 2020.



[4] Zhihao Hu, et al. "Improving Deep Video Compression by Resolution-adaptive Flow Coding", in ECCV(Oral), 2020.

Traditional Motion Compensation Procedure



Formulations

$$\begin{aligned} \mathbf{x}' &:= \text{Bilinear-Warp}(\mathbf{x}, \mathbf{f}) & \text{s.t.} \\ \mathbf{x}'[x, y] &= \mathbf{x}[x + \mathbf{f}_x[x, y], y + \mathbf{f}_y[x, y]] \end{aligned}$$

Limitations

- 1. Rely on existing network architecture
- 2. May need pretrain
- 3. Large residual due to inaccurate warp operation

Traditional Motion Compensation Procedure



Scale-space-warp^[5] motion compensation procedure



Formulations

$$\mathbf{x}' := \text{Scale-Space-Warp}(\mathbf{x}, \mathbf{g}) \qquad \text{s.t.}$$
$$\mathbf{x}'[x, y] = \mathbf{X}[x + \mathbf{g}_x[x, y], y + \mathbf{g}_y[x, y], \mathbf{g}_z[x, y]]$$



• Overall Architecture

Hybrid Coding Approach:

- 1. Scale Space Flow Encoder & Decoder
- 2. Scale Space Warping based Motion Compensation
- 3. Residual Encoder & Decoder

Scale-space flow visulization

Previous reconstruction $\hat{\mathbf{x}}_{i-1}$



Scale Space Warped Prediction $\bar{\mathbf{x}}_i$



Decoded Residual $\hat{\mathbf{r}}_i$



Scale Field \mathbf{g}_z



Final Reconstruction $\hat{\mathbf{x}}_i$







- Existing methods use one previous reference frame
- Exploiting multiple reference frames for learned video compression
 - Directly use multiple frames for motion estimation or motion compensation.
 - Explore the long-range temporal information in latent space

• Exploiting multiple reference frames for learned video compression



• M-LVC: Multiple Frames Prediction for Learned Video Compression



 Maintains a state of arbitrary information learned by the model and jointly compressing all transmitted signals^[7];



 S_{t-1} represents the state from previous time steps and includes the information from both residual and motion.
- The latent representations are generated based on limited reference frames;
- Existing work focus on the *independent* context information only;
 - motion compression and residual compression
- -> exploiting the temporal redundancy to generate latent representations and more accurate context information

• Implicitly explore temporal information in multiple frames







[8] Ren Yang, et al. "Learning for Video Compression with Recurrent Auto-Encoder and Recurrent Probability Model." in submission. This slide is provided by Ren Yang.

• Implicitly explore temporal information in multiple frames



$$H(p_t, q_t) = \mathbb{E}_{\boldsymbol{y}_t \sim p_t} [-\log_2 q_t(\boldsymbol{y}_t | \boldsymbol{y}_1, \dots, \boldsymbol{y}_{t-1})]$$

$$q_t(\boldsymbol{y}_t \mid \boldsymbol{y}_1, \dots, \boldsymbol{y}_{t-1}) = \prod_{i=1}^N q_{it}(y_{it} \mid \boldsymbol{y}_1, \dots, \boldsymbol{y}_{t-1})$$

 $q_{it}(y_{it} | \boldsymbol{y}_1, \dots, \boldsymbol{y}_{t-1}) = \int_{y_{it}=0.5}^{y_{it}=0.5} \text{Logistic}(y; \mu_{it}, s_{it}) dy$

[8] Ren Yang, et al. "Learning for Video Compression with Recurrent Auto-Encoder and Recurrent Probability Model." in submission. This slide is provided by Ren Yang.

• Frame Interpolation based Video Compression



• Frame Interpolation based Video Compression



- L. Extract features from reference images
- 2. Use block based motion estimation
- 3. Interpolate the current frame
- 4. Compress residual using learned image codec
- 5. Compress motion using traditional image codec

Limitations:

- 1. Not end-to-end optimized
- 2. Motion compression is not learnt

• Hierarchical Learned Video Compression (HLVC) with recurrent enhancement ^[1]



The benefits of hierarchical quality are two-fold:

- At encoder side, the high quality frames provide high quality references to improve the compression performance of other frames.
- At decoder side, the low quality frames can be enhanced by taking advantage of high quality frames without bit-rate overhead. It is equivalent to reducing bit-rate on low quality frames.

[10] Ren Yang, et al. "Learning for Video Compression with Hierarchical Quality and Recurrent Enhancement." in CVPR. 2020. This slides is provided by Ren Yang

End-to-End Learned B-Frame Video Compression Hierarchical Learned Video Compression (HLVC) with recurrent enhancement ^[1]



Layer 1:

Compressed by BPG for PSNR model, and by Lee et al. ICLR 2019 for MS-SSIM model.

Layer 2:

Compressed by the proposed Bi-Directional Deep Compression (BDDC) network



[10] Ren Yang, et al. "Learning for Video Compression with Hierarchical Quality and Recurrent Enhancement." in CVPR. 2020. This slides is provided by Ren Yang

End-to-End Learned B-Frame Video Compression Hierarchical Learned Video Compression (HLVC) with recurrent enhancement ^[1]



Compressed by the proposed Single Motion Deep Compression (SMDC) network





Due to the correlation of motions among multiple neighboring frames, we propose using the motion between x_0^C and x_2 to predict the motions between x_1 and x_0^C or x_2 . That is,



As such, x_1 can be compressed with the reference frames of x_0^C and x_2 , without bits consumed for motion map, thus improving the rate-distortion performance.

- Previous works use separate interpolation network and motion compression module
- -> combine interpolation network and motion compression
- The residual is compressed in the pixel domain and it is a non-trivial task.
- -> Feature space residual compression

• Combine interpolation and flow compression and decode the flow and interpolation coefficients simultaneously.



• Residual Compression in Latent Space



Learned Autoencoder based Video Compression

- Previous works follow the hybrid coding framework, i.e., motion compensation and residual coding.
- Using optical flow for explicitly motion estimation
- Separately motion and residual compression

Learned Autoencoder based Video Compression

• Use 3D autoencoders to compress video frames without explicitly motion estimation.



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Discussion

- Open-Source Project
 - Pytorch Data Compression
 - Learned Image Compression
 - Balle, ICLR2017
 - Balle, ICLR2018
 - Minne, NeurlPS2018
 - Learned Video Compression
 - DVC, CVPR2019
 - HU[4], ECCV2020(ongoing)
 - Learned Point Cloud Compression
 - OctSqueeze, CVPR2020



https://github.com/ZhihaoHu/PyTorchDataCompression/

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Q&A

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